A Capacity Scaling Procedure

for the Multi-Commodity

Capacitated Network Design Problem

TOKYO UNIVERSITY OFMINGZHE CHENMARINE SCIENCE ANDTECHNOLOGY

RYUTSU KEIZAI UNIVERSIT

TOKYOUNIVERSITYOFMARINESCIENCEANDTECHNOLOGY

NAOTO KATAYAMA

MIKIO KUBO

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Introduction

- The multi-commodity capacitated network design problem:
- Demands of multi-commodity are given
- Arc capacities are limited
- The total of the design and flow costs is minimized
- The network is configured
- Flow paths are decided
- Strong and weak, path type formulationsColumn generation technique
- Capacity scaling procedure
 - IFORSZEG PROPOSED in this study 2

The multi-commodity capacitated network design model



Node: Distribution center, break bulk point, end-of-line point, computer

Arc : less-than-truckload service, feeder service, communication line

Flow: Freights, communication data

The multi-commodity capacitated network design model



Node : Distribution center, break bulk point, end-of-line point, computer

Arc: less-than-truckload service, feeder service, communication line

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Literatures

- Crainic–Gendron–Hernu (2003)
 The slope scaling method, changing the flow cost on the weak formulation
 The slope scaling solution method by the Lagrange relaxation method and the long term memory
 Crainic–Gendreau–Farvolden (2000)
 The column generation technique
 The taboo search method for the base transformation at a simplex method
- Ghamlouche–Crainic–Gendreau (2002, 2003) The cycle based neighborhood structure The path relinking method

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Notations

- $\square N$:set of nodes
 - A :set of arcs
 - $\blacksquare K$:set of commodities
 - $\blacksquare P^k$:set of paths from origins to destinations for commodity k
 - $\blacksquare P'^k \text{subset of path } P^k$
 - d^k:demand for commodity k
 - c_{ij}^k : unit cost for commodity on $\operatorname{arc}(i, j)$

Notations

- $f_{ij}: \text{design cost of } \operatorname{arc}(i, j)$
 - $\square C_{ij} : \text{capacity of } \operatorname{arc}(i, j)$
 - δ_{ijp} : 1, if arc (i, j) is included in path, otherwise 0.
 - x_p^k :flow of commodity k on path p, continuous nonnegative variable
 - \checkmark $y_{ij:1, if arc}(i, j)$ is selected, otherwise 0, binary variable

Strong Path flow Formulation





Design costs of arcs



Formulation



Formulation



 $\sum_{p \in P^k} \delta_{ijp} x_p^k \le d^k y_{ij} \quad (i, j) \in A \quad k \in K$

Path flow on arc (*i*,*j*) for commodity *k* can not exceed its demand. Without these constraints MCND(P) becomes a weak formulation

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The total of path flows for commodity *k* equals to its demand



Formulation using P', subset of P

$(MCND(P')) \quad \min \quad \sum_{(i,j)\in A} \sum_{k\in A} c_{ij}^k \sum_{p\in P'^k} \delta_{ijp} x_p^k + \sum_{(i,j)\in A} f_{ij} y_{ij}$

(2)**s.t.** $\sum_{k \in K} \sum_{p \in P'^k} \delta_{ijp} x_p^k \leq C_{ij} y_{ij}$ $(i, j) \in A$

 $\sum_{p \in P'^k} \delta_{ijp} x_p^k \le d^k y_{ij} \qquad (i,j) \in A \qquad k \in K$ (3)

 $p \in P^{k}$

 $(i, j) \in A$

$\sum x_p^k = d^k$	$k \in K$
$p \in P'^k$	

 $k \in K$

Without these constraints MCND(P) becomes a weak formulation

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 $y_{ij} \in \{0,1\}$

 $x_p^k \ge 0$

(6)

(4)

(5)

(1)

- Solve the linear relaxation problem
 - Change the capacities of arcs based on solutions of LP relaxation and previous capacities and solve LP
 - Iterate above procedures, until the design variables y converge at 0 or 1
- Solve the multi-commodity flow problem with fixed design variable y, based on convergent solutions





Once *C*' is less than the optimal solution x^* , the optimal solution can never be obtained. IFORS2005 HAWAII 15





Column generation

When the numbers of arcs and commodities become large, the number of paths may increase extremely



At first, solve LP using

the subset of paths, P'

If necessary, generate paths (columns),

Add columns to LP and solve LP again



Column generation -Reduced cost

Using dual variables, substitute constraints (2),(3),(4) into the objective function



All coefficients of x : nonnegative at the optimal solution
Coefficient : the reduced cost for x.
Solve the pricing problem
Decide whether the reduced cost is negative or nonnegative.

Column generation -Reduced cost



Column generation - Pricing problem

- For each commodity,
- Pricing problem : shortest path problem



If the reduced cost is negative, then this shortest path is added as a path flow variable. IFORS2005 HAWAII

Procedure of column generation

- 1) Obtain the set of paths for every commodity *k*, and defined it as *P*^{'k}
- 2) Solve *MCNDR(P'*), obtain dual variables
- $\pi_{ij}, \sigma_{ij}^{k}, \beta_{k}$ 3) For all commodities do
 - a) Let the arc cost be (c^k_{ij}+π_{ij} + σ^k_{ij}), and solve the shortest path problem for commodity k, then obtain the value of h^k_p
 b) If h^k_p < 0, add the path to P'^k

4) If paths are add to P, go to 2); Otherwise, end

Row generation

The number of forcing constraints is depended on the product space of arcs and commodities

 $\sum_{p \in P'^k} \delta_{ijp} x_p^k \le d^k y_{ij} \qquad (i, j) \in A \qquad k \in K$ (3)

- For example, 500 arcs, 100 commodities, forcing constraints is up to 50000
- When columns are generated, forcing constraints (rows) correspond to columns are added.

Row generation



- Let MCNDR(C) be the problem with arc capacity C
- 1) Define the smoothing parameter as $\lambda \in (0,1]$, and let *C*' be *C*
- 2) Iterate to solve MCNDR(C'), until y converges at 0 or 1
 - a) Change the domain of y to [0, C/C']
 - b) Solve MCNDR(C') by column generation, obtain solutions x, y
 - c) Update $C' := \lambda C' y + (1 \lambda) C'$
- 3) Obtain the approximate solution and the upper bound from the convergence solution.

Numerical Experiments

- Experiment environments
- Data: Multi-commodity Network Design Problems in OR-Library: Problem Mulgen I from p33 to p50
 Computer: Pentium 4, 2.8GHz, RAM 750Mb
 - Language: C
- Software for solving LP: GLPK ver.4.1
- Lower bounds by CPLEX (max CPU time 10 hours)
 - for gaps

Computational Results

Table 1. Computational results

Names of	Number of	Number of	Number of	The weak		The strong	
Problems	Nodes	Arcs	Commodities	gaps	time	gaps	time
p33	20	230	40	0.3%	0:00:02	0.0%	0:00:03
p34	20	230	40	3.3%	0:00:03	0.0%	0:00:04
p35	20	230	40	0.2%	0:00:03	0.0%	0:00:03
p36	20	230	40	1.9%	0:00:03	0.6%	0:00:04
p37	20	229	200	9.1%	0:00:08	4.8%	1:27:42
p38	20	229	200	7.6%	0:00:07	3.4%	8:36:00
p39	20	229	200	10.5%	0:00:07	2.6%	1:27:03
p40	20	229	200	10.8%	0:00:11	5.1%	14:42:02
p41	20	289	40	0.8%	0:00:04	0.3%	0:00:05
p42	20	289	40	2.4%	0:00:04	0.1%	0:00:08
p43	20	289	40	0.6%	0:00:02	0.3%	0:00:03
p44	20	289	40	2.3%	0:00:03	0.6%	0:00:04
p45	20	287	200	11.4%	0:00:08	3.9%	1:48:42
p46	20	287	200	8.3%	0:00:12	6.0%	11:54:52
p47	20	287	200	9.6%	0:00:07	3.3%	0:57:36
p48	20	287	200	9.2%	0:00:14	6.8%	7:43:39
p49	30	517	100	3.6%	0:00:09	1.1%	0:01:42
p50	30	517	100	18.4%	0:00:04	6.9%	51:24:35

Computational time: hours:minutes:seconds

Conclusion

This study considered the multi-commodity capacitated network design problem

- Path type weak and strong formulations were presented
- A capacity scaling procedure combined with column generation was proposed
- The effectiveness of the formulation and solution procedure was tested by numerical experiments