

A Capacity Scaling Procedure for the Multi-Commodity Capacitated Network Design Problem

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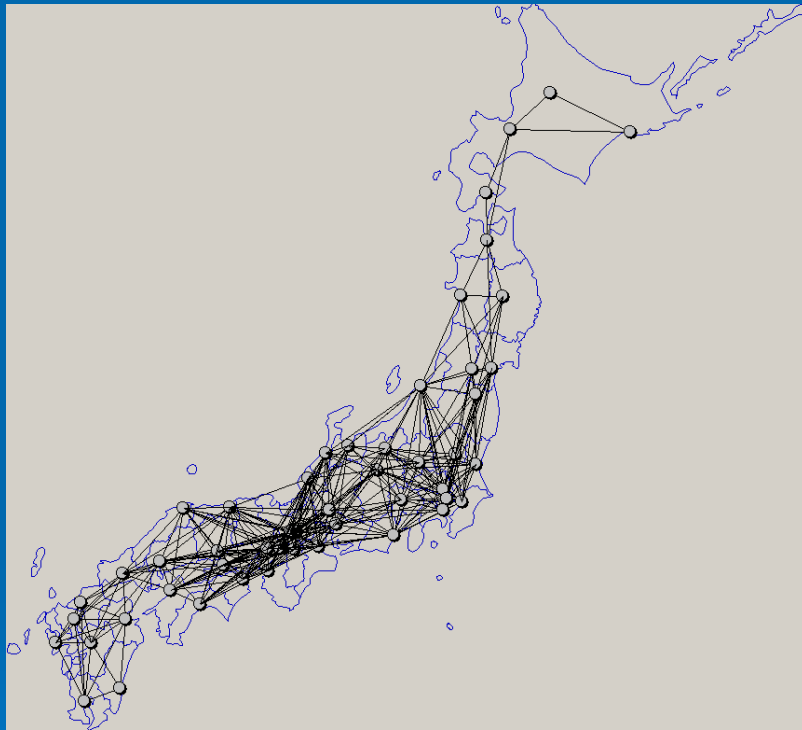
Multi-Commodity Network Design Problem

- The basic model for transportation network design, communication network design, traffic network design and etc.
- Given nodes, arcs, multi-commodities, costs, demands and side constraints,
- Select arcs to be minimized the total cost.
- Find paths for commodities.

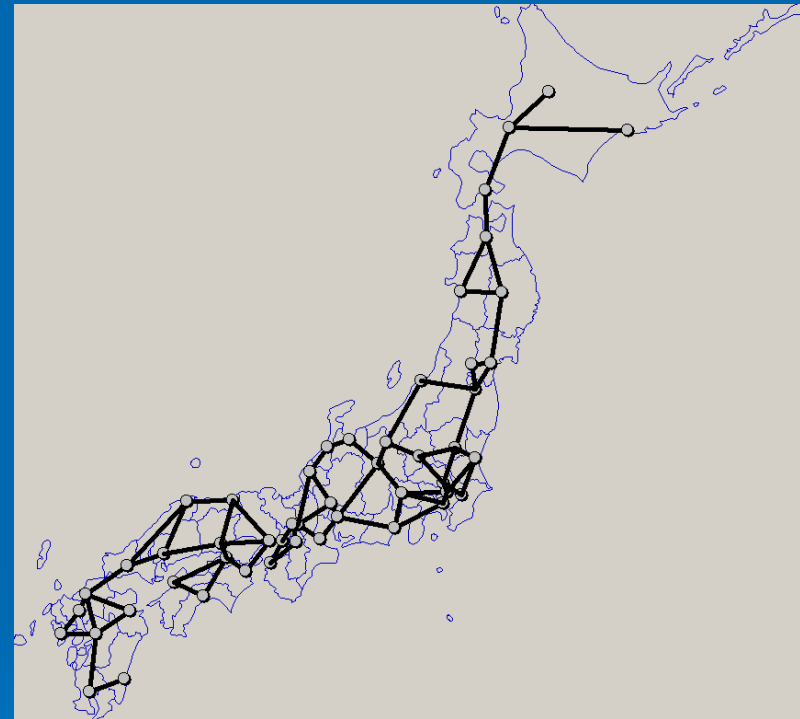
Multi-Commodity Network Design Problem

- Budget network design problem
- Fixed charge network design problem
- **Capacitated network design problem**
- User equilibrium network design problem
- Hub network design problem
- Less-than-truckload problem

Multi-Commodity Network Design Problem



Select arcs



Japanese express highway design; Budget network design,
Total length 9000Km, 50 nodes, 654 arcs, 1225
commodities, 1.3million variables (katayama2003)

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Capacitated Network Design Problem (CND)

- Capacitated network design problem:
 - Large size mixed integer problem
 - NP-hard
- Need to develop approximation methods to solve CND.
- Propose:
 - For a strong path type formulation,
 - A capacity scaling procedure
 - With column and row generation techniques.

Capacitated Network Design Problem (CND)

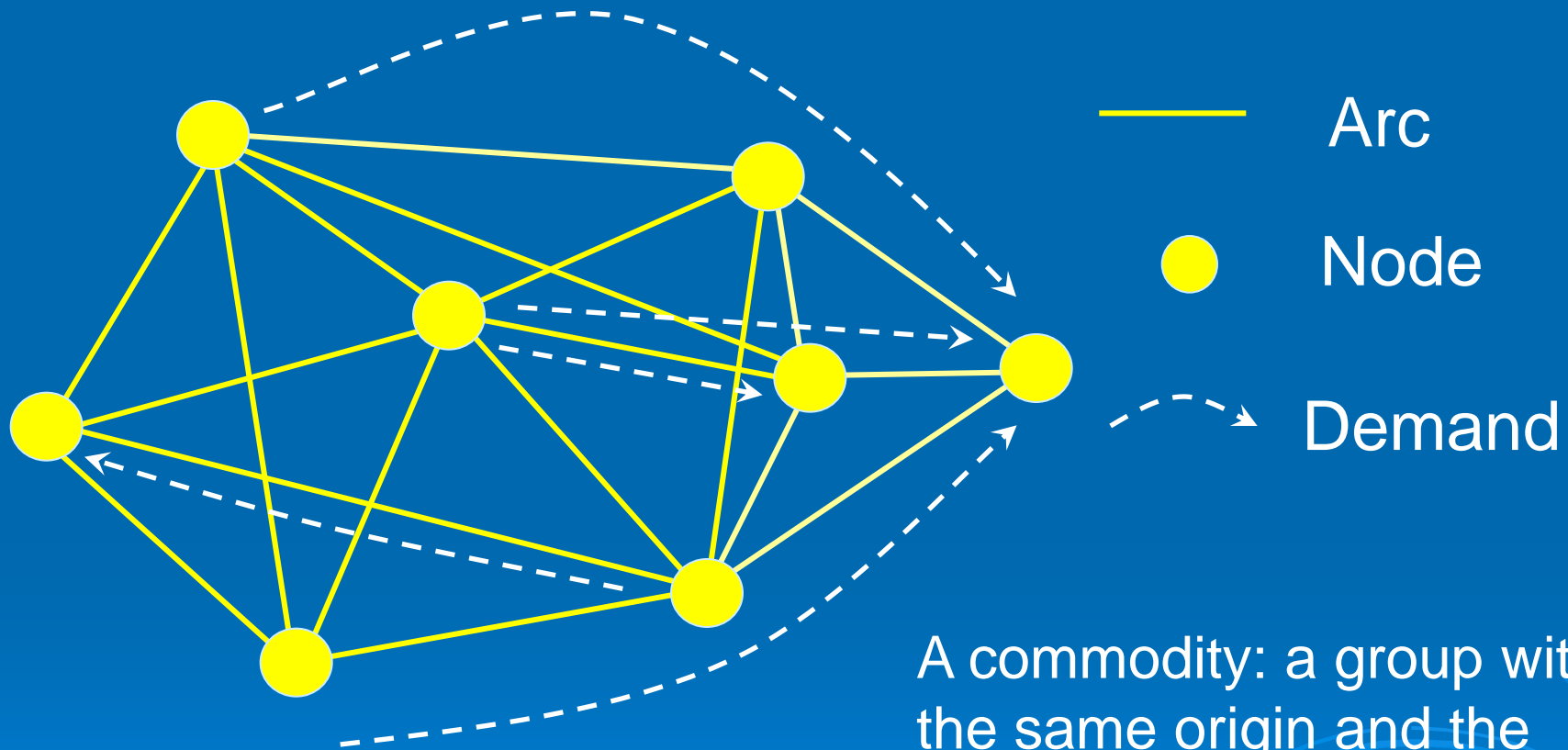
➤ Given:

- The set of nodes and the set of arcs,
- The set of multi-commodities and demands,
- Arc design costs and arc flow costs,
- Arc capacities.

➤ Find:

- A network configuration; selected arcs,
- Path flows for each commodity
- The total of design and flow costs should be minimized.

Capacitated Network Design Problem



A commodity: a group with the same origin and the same destination.

Capacitated Network Design Problem



Literatures: Valid inequality

- Katayama(1992)
Cut-set inequality, detour inequality
- Magnanti-Mirchandani(1993)
Cut-set inequality, three-partition inequality,
arc residual capacity inequality
- Barahona(1996)
Valid inequalities, multi-cut inequality
- Chouman-Crainic-Gendron(2003)
Cut-set inequalities and lifting

Lower bound

- Katayama(1993)
 - Dual ascent method for integer rounding cuts with weak cut-set formulation
- Gendron-Crainic(1994,1996)
 - Lagrange relaxation method for capacity and/or flow conservation constraints
- Herrmann-Ioannou-Minis(1996)
 - Dual ascent method
- Crainic-Frangioni-Gendron(1998)
 - Bundle-based Lagrange relaxation method
- Katayama(2003)
 - Lagrange multiplier adjustment method for a strong and cut-set formulation
- Chouman-Crainic-Gendron(2003)
 - Linear relaxation for cut-set inequalities and lifting

Heuristics

- Gendron-Crainic(1994,1996)
Resource decomposition heuristics
- Holmberg-Yuan(2000)
A Lagrange heuristic based branch and bound method
- Crainic-Gendreau-Farvolden(2000)
Simplex-based tabu search heuristics
- Crainic-Gendreau(2002)
Cooperative parallel tabu search heuristics
- Ghamlouche-Crainic-Gendreau(2003)
Cycle based neighborhood search heuristics
- Crainic-Gendron-Hernu(2003)
Slope scaling and Lagrange perturbation heuristics for a weak formulation
- Ghamlouche-Crainic-Gendreau(2002,2004)
Path relinking heuristics

Notations

- N :set of nodes
- A :set of arcs
- K :set of commodities
- P : set of paths
- P^k :set of paths for commodity k
- P_i^k :subset of path for k
- d^k :demand for commodity k
- c_{ij}^k :unit flow cost for commodity on arc (i, j)
- f_{ij} :arc design cost of arc (i, j)
- C_{ij} :arc capacity of arc (i, j)
- δ_{ijp} :1, if arc (i, j) is included in path, otherwise 0
- x_p^k : continuous path flow variable of commodity k on path p
- y_{ij} : binary arc design variable 1, if arc (i, j) is selected, otherwise 0,

Strong Path Flow Formulation

$$(CND) \quad \min \sum_{(i,j) \in A} \sum_{k \in A} c_{ij}^k \sum_{p \in P^k} \delta_{ijp} + \sum_{(i,j) \in A} f_{ij}$$
$$st \quad \sum_{k \in K} \sum_{p \in P^k} \delta_{ijp} x_p^k \leq C_{ij} y_{ij} \quad (i,j) \in A$$
$$\sum_{p \in P^k} x_p^k = d^k \quad k \in K$$
$$\sum_{p \in P^k} \delta_{ijp} x_p^k \leq d^k y_{ij} \quad (i,j) \in A \quad k \in K$$
$$x_p^k \geq 0 \quad k \in K \quad p \in P^k$$
$$y_{ij} \in \{0,1\} \quad (i,j) \in A$$

Strong Path Flow Formulation

$$(CND) \quad \min \sum_{(i,j) \in A} \sum_{k \in A} c_{ij}^k \sum_{p \in P^k} \delta_{ijp} x_p^k + \sum_{(i,j) \in A} f_{ij} y_{ij}$$

Flow costs

Arc design costs

Strong Path Flow Formulation

Arc capacity constraints

$$st \quad \sum_{k \in K} \sum_{p \in P^k} \delta_{ijp} x_p^k \leq C_{ij} y_{ij} \quad (i, j) \in A$$

$$\sum_{p \in P^k} x_p^k = d^k \quad k \in K$$

Flow conservation constraints

Strong Path Flow Formulation

Forcing constraints for each arc and commodity

$$\sum_{p \in P^k} \delta_{ijp} x_p^k \leq d^k y_{ij} \quad (i, j) \in A \quad k \in K$$

Tight and strong valid constraints

$$x_p^k \geq 0 \quad k \in K \quad p \in P^k$$

$$y_{ij} \in \{0,1\} \quad (i, j) \in A$$

Strong Path Flow Formulation

- A large mixed integer problem
 - The number of integer design variables is $O(|A|)$
 - The number of flow variables is $O(|K| \cdot |A|)$
- Fixed design variables, a tight multi-commodity network flow problem; not so easy problem.
- The linear relaxation problem is not so easy problem.
- The linear relaxation problem without forcing constraints is an easy problem.

Strong Path Flow Formulation

- The number of path flow variables is huge.

$$O(|K| \cdot |A|!)$$

- A column generation technique

- Forcing constraints for each arc and commodity are tight valid inequalities.

- The number of forcing constraints is large.

$$O(|K||A|) = (|N|^4)$$

- A row generation technique

Capacity Scaling Procedure

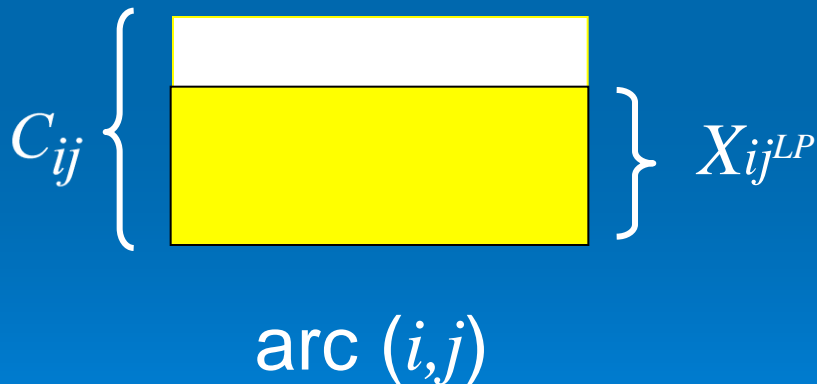
- An approximation method for capacitated problems
- Until design variables y converge to 0 or 1.
 - Solve the linear relaxation problem (LP).
 - Change arc capacities based on a solution of LP and previous capacities.
- Solve the multi-commodity flow problem where all design variables y are fixed to the convergent solutions.

Linear Relaxation Problem

$$\begin{aligned} (LP) \quad & \min \sum_{(i,j) \in A} \sum_{k \in A} c_{ij}^k \sum_{p \in P^k} \delta_{ijp} + \sum_{(i,j) \in A} f_{ij} \\ & \text{st} \quad \sum_{k \in K} \sum_{p \in P^k} \delta_{ijp} x_p^k \leq C_{ij} y_{ij} \quad (i,j) \in A \\ & \quad \sum_{p \in P^k} x_p^k = d^k \quad k \in K \\ & \quad \sum_{p \in P^k} \delta_{ijp} x_p^k \leq d^k y_{ij} \quad (i,j) \in A \quad k \in K \\ & \quad x_p^k \geq 0 \quad k \in K \quad p \in P^k \\ & \quad 0 \leq y_{ij} \leq 1 \quad (i,j) \in A \end{aligned}$$

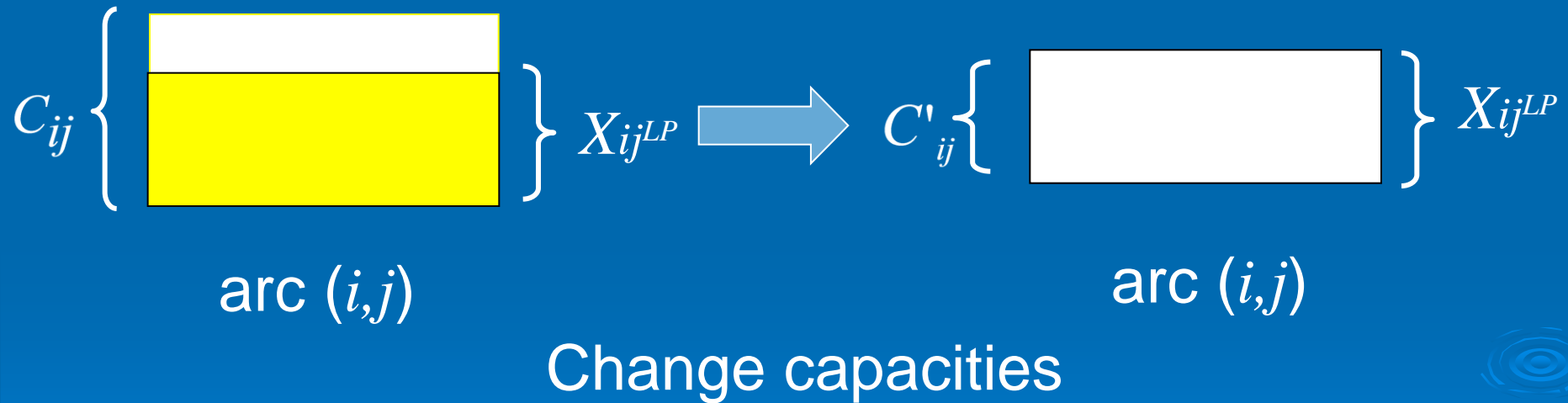
Capacity Scaling Procedure

- Solve the linear relaxation problem
- Obtain LP solution y_{ij}^{LP} , X_{ij}^{LP} ($= \sum_{k \in K} \sum_{p \in P^k} \delta_{ijp} x_p^k$ arc flow)
- y_{ij}^{LP} may be a fraction between 0 and 1.



Capacity Scaling Procedure

- Solve the linear relaxation problem
- LP solution y_{ij}^{LP} , X_{ij}^{LP} ($= \sum_{k \in K} \sum_{p \in P^k} \delta_{ijp} x_p^k$, arc flow)



Capacity Scaling Procedure

- If all flow variables X_{ij}^{LP} are the optimal flows for *CND*, the optimal design variables for the problem changed capacities are equivalent to the optimal design variables for *CND*
- If the optimal capacities (= the optimal flow values) were found, the optimal solution for *CND* could be obtained.
- If capacities can be close to the optimal flow values bit at a time, good approximate solutions may be obtained.

Capacity Scaling Procedure

- Relationship between X and y

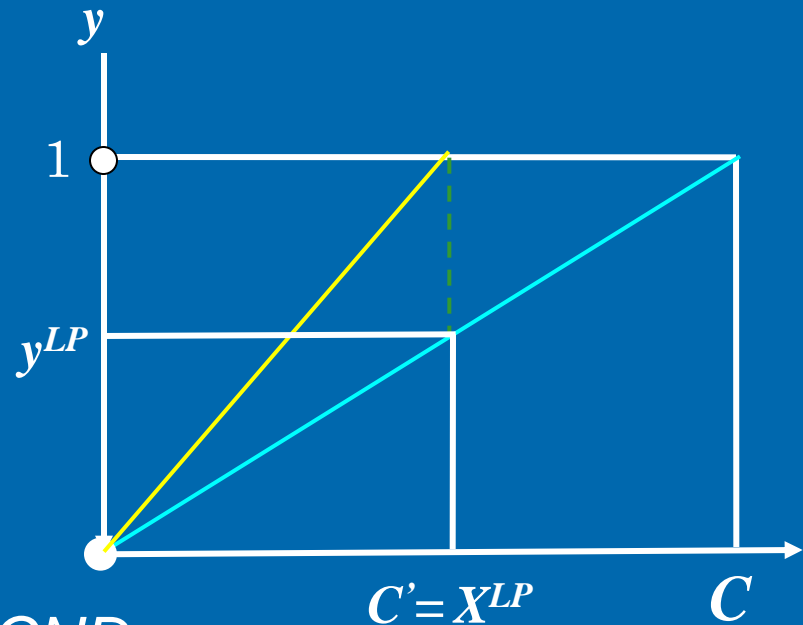
$$X_{ij} \leq C_{ij} y_{ij}, X_{ij} \geq 0, y_{ij} = \{0,1\}$$

- Relationship between X and y at the optimal solutions for LP

$$X_{ij}^{LP} \approx C_{ij} y_{ij}^{LP}, X_{ij}^{LP} \geq 0, 0 \leq y_{ij}^{LP} \leq 1$$

- Assume X^{LP} is the optimal flow for CND

- Change capacity C to $C'_{ij} = X_{ij}^{LP}$



Capacity Scaling Procedure

- Change capacity C' by the smoothing parameter λ
- Prevent large change of C' and flows

$$C'_{ij} = \lambda X_{ij}^{LP} + (1 - \lambda)C'_{ij}$$

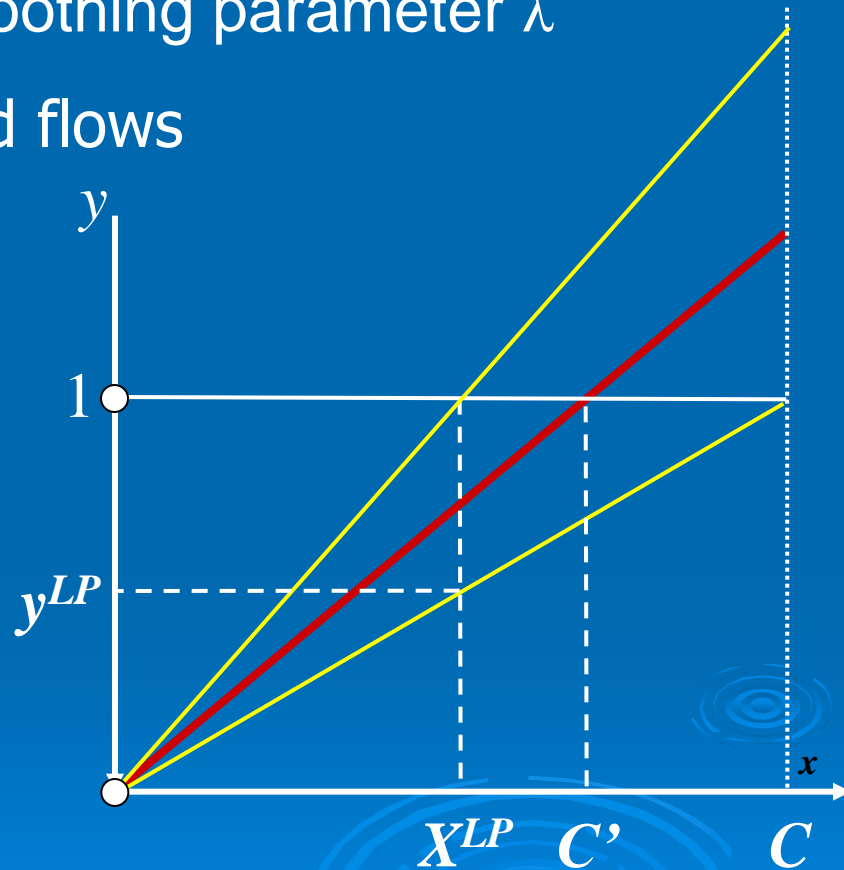
- Change the upper bound of y

$$0 \leq X_{ij} \leq C_{ij}$$

$$0 \leq C'_{ij} y_{ij} \leq C_{ij}$$

↓

$$0 \leq y_{ij} \leq \frac{C_{ij}}{C'_{ij}}$$



Capacity Scaling Procedure

$$(CND(C')) \quad \min \sum_{(i,j) \in A} \sum_{k \in K} c_{ij}^k \sum_{p \in P^k} \delta_{ijp} x_p^k + \sum_{(i,j) \in A} f_{ij} y_{ij}$$

$$st \quad \sum_{k \in K} \sum_{p \in P^k} \delta_{ijp} x_p^k \leq C'_{ij} y_{ij} \quad (i,j) \in A$$

$$\sum_{p \in P^k} \delta_{ijp} x_p^k \leq d^k y_{ij} \quad (i,j) \in A, k \in K$$

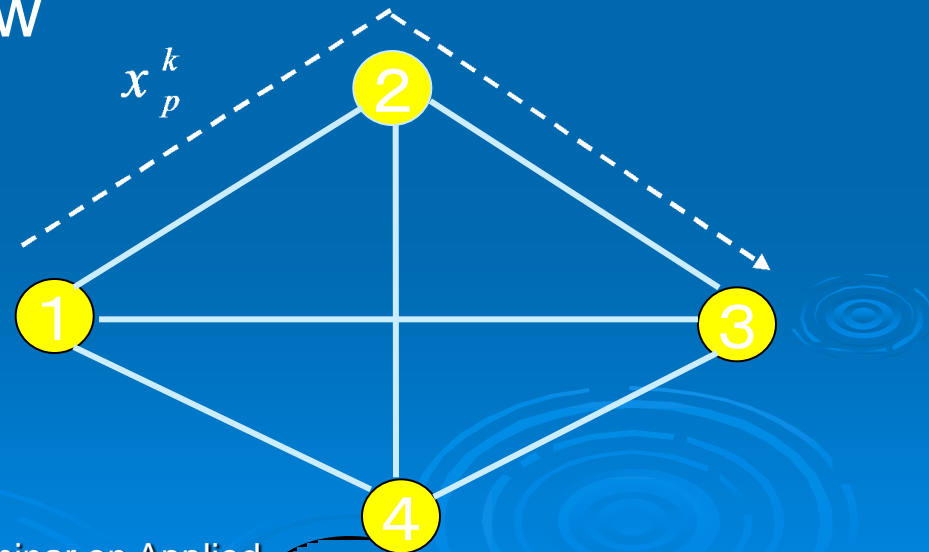
$$\sum_{p \in P^k} x_p^k = d^k \quad k \in K$$

$$x_p^k \geq 0 \quad k \in K, p \in P^k$$

$$0 \leq y_{ij} \leq C_{ij} / C'_{ij} \quad (i,j) \in A$$

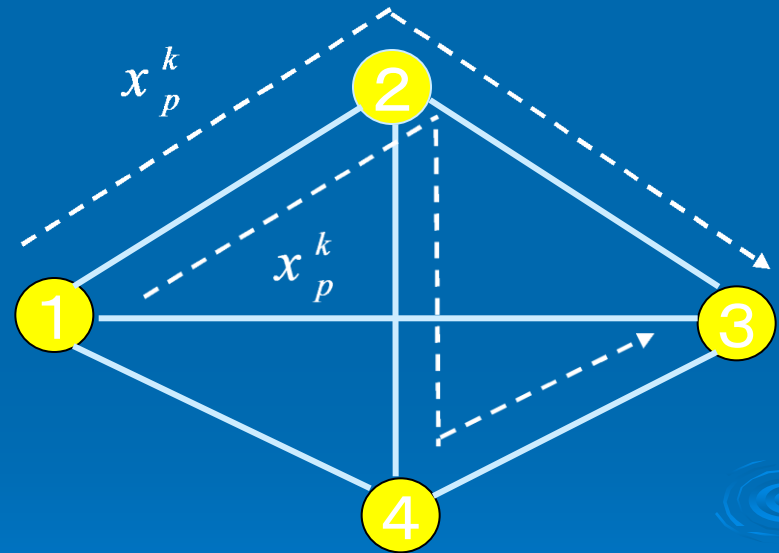
Column generation

- The number of paths may be huge.
- Solve LP with the subset of paths, P' instead of P .
- If not optimal:
 - Generate new path flow variables (columns),



Column generation

- The number of paths may be huge.
- Solve LP with the subset of paths P' instead of P .
- If not optimal:
 - Generate new path flow variables (columns),
 - Add paths to LP as columns,
 - Solve LP again.



Restricted primal problem

$$(CND(C', P')) \quad \min \sum_{(i,j) \in A} \sum_{k \in K} c_{ij}^k \sum_{p \in P^k} \delta_{ijp} x_p^k + \sum_{(i,j) \in A} f_{ij} y_{ij}$$

$$\pi_{ij} \dots \quad st \quad \sum_{k \in K} \sum_{p \in P^k} \delta_{ijp} x_p^k \leq C_{ij}^n y_{ij} \quad (i,j) \in A$$

$$\sigma_{ij}^k \dots \quad \sum_{p \in P^k} \delta_{ijp} x_p^k \leq d^k y_{ij} \quad (i,j) \in A, k \in K, \sum_{p \in P^k} \delta_{ijp} > 0$$


$$\mu^k \dots \quad \sum_{p \in P^k} x_p^k = d^k \quad k \in K$$

$$x_p^k \geq 0 \quad k \in K, p \in P^k$$

$$0 \leq y_{ij} \leq C_{ij} / C_{ij}^n \quad (i,j) \in A$$

Column generation - Reduced cost

- Using dual variables, substitute constraints into the objective function

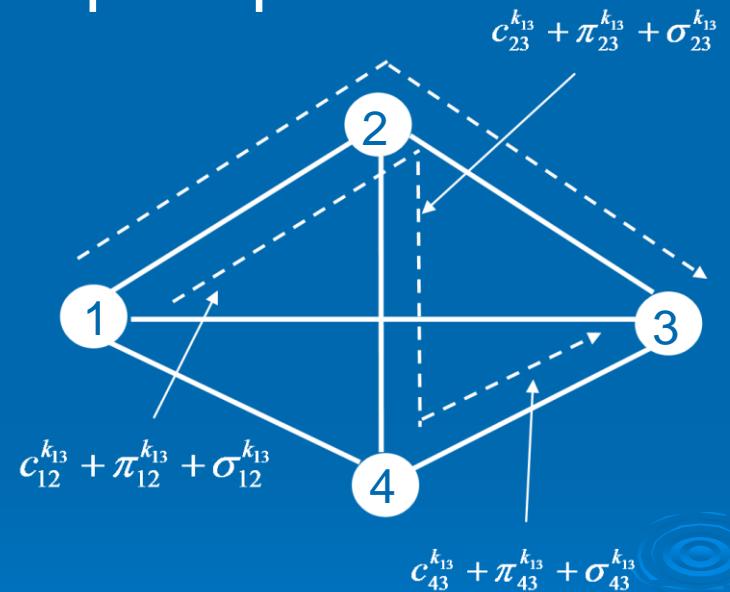
$$\sum_{k \in K} \sum_{p \in P^k} \left[\sum_{(i,j) \in A} \underbrace{(c_{ij}^k + \pi_{ij} + \sigma_{ij}^k)}_{\text{reduced cost}} \delta_{ijp} - \mu^k \right] x_p^k + \sum_{(i,j) \in A} (f_{ij} - \pi_{ij} C_{ij} - \sum_{k \in K} \sigma_{ij}^k d^k) y_{ij} + \sum_{k \in K} \mu^k d^k$$


- All coefficients (reduced costs) of x_p^k should be nonnegative at the optimal solution.
- Solve a pricing problem, find new x_p^k such that a reduced cost is negative.

Column generation - Reduced cost

- For each commodity k ,
 - A pricing problem is shortest path problem

$$\begin{aligned}
 \min \quad & \sum_{(i,j) \in A} (c_{ij}^k + \pi_{ij} + \sigma_{ij}^k) z_{ij} - \mu^k \\
 \text{st} \quad & \sum_{j \in N} z_{ij} - \sum_{j \in N} z_{ji} = \begin{cases} -1 & i = O^k \\ 1 & i = D^k \\ 0 & i \in N \setminus \{O^k, D^k\} \end{cases} \\
 & z_{ij} \in \{0,1\} \quad (i,j) \in A
 \end{aligned}$$



- If the reduced cost of the optimal length is negative, this shortest path is a new column.

Row generation

- The number of forcing constraints is $O(|K||A|)$

$$\sum_{p \in P^k} \delta_{ijp} x_p^k \leq d^k y_{ij} \quad (i, j) \in A, k \in K$$

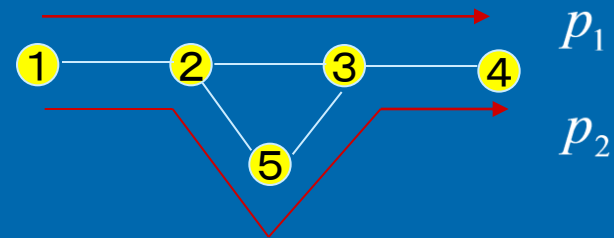
- When columns are generated, forcing constraints (rows) corresponding to these columns are only generated.

Row generation

p_1 : Initial path: $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$



Generated path p_2 : $1 \rightarrow 2 \rightarrow 5 \rightarrow 3 \rightarrow 4$



$$\begin{cases} x_{p_1}^k \leq d^k y_{12} \\ x_{p_1}^k \leq d^k y_{23} \\ \vdots \\ x_{p_1}^k \leq d^k y_{34} \end{cases}$$

Generated column

$$\begin{aligned} x_{p_1}^k + x_{p_2}^k &\leq d^k y_{12} \\ x_{p_1}^k &\leq d^k y_{23} \\ x_{p_1}^k + x_{p_2}^k &\leq d^k y_{34} \end{aligned}$$

Generated rows

$$\begin{aligned} x_{p_2}^k &\leq d^k y_{25} \\ x_{p_2}^k &\leq d^k y_{53} \end{aligned}$$

$$\sum_{p \in P^k} \delta_{ijp} x_p^k \leq d^k y_{ij}$$

Capacity Scaling Procedure

- Even if using column and row generation techniques, it takes long time to solve $CND(C',P')$.
- As design variables change by capacity scaling procedure, the column and row generation are iterated.
- If all design variables converge to 0 or 1, we solve a multi-commodity flow problem fixed all design variables and an upper bound and an approximate solution are obtained.
- There is no guarantee such that all design variables converge to 0 or 1.
- It takes much iteration until most design variables converge to 0 or 1.

Capacity Scaling Procedure

- If the number of free design variables (not converge to 0 or 1) is less than the certain number, then branch-and-bound method is applied to the problem with free design variables.
- If the number of free design variables is small (e.g. 75-100), the problem can be solve easily by CPLEX.
- After the maximum iteration number, solve the multi-commodity flow problem fixed all design variables by an arc flow formulation exactly and an upper bound is obtained.

Capacity Scaling Procedure

- 1) Set $\lambda \in (0,1]$, B and an initial path set P' , and $C' := C$,
- 2) Until exceed the maximum iteration number and the number of free design variables is less than B ;
 - a) Solve $CND(C', P')$ by column and row generation, obtain solutions.
 - b) Change capacities C' and upper bounds of y .
 - c) When the number of free design variables is less than B , solve the problem with free design variables by a branch-and-bound method and obtain an upper bound.
- 3) Solve the multi-commodity flow problem fixed all design variables by an arc flow formulation and obtain an upper bound.

Numerical Experiments

- Data: Crainic et al. (2000,2003,2004)
Bench mark data for CND
- Computer: Pentium 4, 3.2GHz, RAM 1Gb
- Language: Visual Basic.NET
- Software for solving LP and branch-and-bound : CPLEX 9.0
- Smoothing parameter λ :
0.025,0.050,0.075,0.100,0.125,0.150
- The minimum number of variables when applying a branch-and-bound method: 75
- The maximum iteration number: 40

Numerical Experiments

Table 1. Computational Results (Type C problem)

Node	Arc	Commodity	Fixed Cost	Capacity	Best Upper Bound	Capacity Scaling	Difference	Improvement
20	100	10	V	L	14,712	14,712	0	0.00%
20	100	10	F	L	14,941	15,037	96	-0.64%
20	100	10	F	T	49,899	50,771	872	-1.75%
25	100	30	V	T	365,272	365,272	0	0.00%
25	100	30	F	L	37,515	37,471	-44	0.12%
25	100	30	F	T	86,296	85,801	-495	0.57%
20	230	40	V	L	424,385	424,075	-310	0.07%
20	230	40	V	T	371,475	371,906	431	-0.12%
20	230	40	F	T	644,172	644,483	311	-0.05%
20	300	40	V	L	429,398	429,398	0	0.00%
20	300	40	F	L	589,190	587,800	-1390	0.24%

- Best Upper Bound: the best known bound; Simplex-Based Tabu, Cycle-Based Neighborhoods, Path Relinking, Multilevel Cooperative Tabu

Numerical Experiments

Table 2. Computational Results (Type C problem)

Node	Arc	Commodity	Fixed Cost	Capacity	Best Upper Bound	Capacity Scaling	Difference	Improvement
20	300	40	V	T	464,509	464,569	60	-0.01%
20	300	40	F	T	606,364	604,198	-2166	0.36%
20	230	200	V	L	98,582	94,247	-4335	4.40%
20	230	200	F	L	143,150	137,642	-5508	3.85%
20	230	200	V	T	102,030	97,968	-4062	3.98%
20	230	200	F	T	141,188	136,130	-5059	3.58%
20	300	200	V	L	78,184	74,913	-3271	4.18%
20	300	200	F	L	121,951	115,784	-6168	5.06%
20	300	200	V	T	77,251	75,302	-1949	2.52%
20	300	200	F	T	111,173	107,858	-3316	2.98%
100	400	10	V	L	28,485	28,426	-59	0.21%
100	400	10	F	L	23,949	24,459	510	-2.13%
100	400	10	F	T	65,278	73,566	8288	-12.70%
100	400	30	V	T	384,926	384,883	-43	0.01%
100	400	30	F	L	50,456	51,956	1500	-2.97%
100	400	30	F	T	141,359	144,314	2955	-2.09%

Numerical Experiments

Table 3. Computational Results (Type C problem)

Node	Arc	Commodity	Fixed Cost	Capacity	Best Upper Bound	Capacity Scaling	Difference	Improvement
30	520	100	V	L	54,904	54,088	-816	1.49%
30	520	100	F	L	99,586	94,801	-4785	4.80%
30	520	100	V	T	52,985	52,282	-703	1.33%
30	520	100	F	T	102,477	98,839	-3638	3.55%
30	700	100	V	L	48,398	47,635	-763	1.58%
30	700	100	F	L	62,471	60,194	-2277	3.64%
30	700	100	V	T	47,025	46,169	-856	1.82%
30	700	100	F	T	56,576	55,359	-1217	2.15%
30	520	400	V	L	115,671	112,846	-2825	2.44%
30	520	400	F	L	156,601	149,446	-7155	4.57%
30	520	400	V	T	120,170	114,641	-5530	4.60%
30	520	400	F	T	160,217	152,744	-7474	4.66%
30	700	400	V	L	102,631	97,972	-4659	4.54%
30	700	400	F	L	143,988	135,064	-8924	6.20%
30	700	400	V	T	99,195	95,306	-3889	3.92%
30	700	400	F	T	138,266	130,148	-8118	5.87%
AVERAGE					168,076	166,058	-2,018	1.55%

Numerical Experiments

Table 4. Computational Times (Type C problem; seconds)

Node	Arc	Commodity	Fixed Cost	Capacity	Simplex Tabu	Cycle Based	Path Relinking	Capacity Scaling
20	100	10	V	L	6	19	13	1
20	100	10	F	L	8	22	14	8
20	100	10	F	T	17	34	24	3
25	100	30	V	T	17	142	101	3
25	100	30	F	L	33	112	75	18
25	100	30	F	T	72	133	97	13
20	230	40	V	L	71	214	149	3
20	230	40	V	T	90	241	157	4
20	230	40	F	T	122	260	172	4
20	300	40	V	L	71	305	225	3

- Simplex-Based Tabu, Cycle-Based Neighborhoods, Path Relinking:

Sun Enterprise 10000 400Mz with 64CPU

- Capacity Scaling: Pentium4 3.2GHz

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Numerical Experiments

Table 5. Computational Times (Type C problem ; seconds)

Node	Arc	Commodity	Fixed Cost	Capacity	Simplex Tabu	Cycle Based	Path Relinking	Capacity Scaling
20	300	40	F	L	113	336	228	6
20	300	40	V	T	145	379	248	4
20	300	40	F	T	123	349	214	5
20	230	200	V	L	505	2586	2495	503
20	230	200	F	L	492	3142	2878	1193
20	230	200	V	T	548	2730	2211	931
20	230	200	F	T	890	3634	3386	1122
20	300	200	V	L	982	4086	3566	676
20	300	200	F	L	1317	4210	4013	3691
20	300	200	V	T	938	4204	3924	755
20	300	200	F	T	1066	4855	3857	4163
100	400	10	V	L	33	252	89	6
100	400	10	F	L	33	197	83	78
100	400	10	F	T	81	451	210	32
100	400	30	V	T	278	1200	493	30
100	400	30	F	L	100	717	315	384
100	400	30	F	T	216	1301	481	100

Numerical Experiments

Table 6. Computational Times (Type C problem ; seconds)

Node	Arc	Commodity	Fixed Cost	Capacity	Simplex Tabu	Cycle-Based	Path Relinking	Capacity Scaling
30	520	100	V	L	996	2261	1194	35
30	520	100	F	L	939	2684	1460	324
30	520	100	V	T	1219	2716	1514	47
30	520	100	F	T	670	2892	1523	148
30	700	100	V	L	1265	2960	1861	34
30	700	100	F	L	1480	3182	1838	123
30	700	100	V	T	2426	3746	1894	44
30	700	100	F	T	1736	3547	1706	79
30	520	400	V	L	5789	55771	27477	885
30	520	400	F	L	6407	40070	36669	3087
30	520	400	V	T	6522	4679	23089	260
30	520	400	F	T	8415	49887	52173	1154
30	700	400	V	L	12636	38857	22315	424
30	700	400	F	L	11368	68214	75665	1398
30	700	400	V	T	15880	51764	24289	634
30	700	400	F	T	11660	79053	44936	1573
				AVERAGE	2274	10428	8124	558

Numerical Experiments

Table 7. Gaps (Type R problem, 153 problems)

Capacity Level	Fixed Cost Level	Simplex Tabu	Cycle Based	Path Relinking	Cooperative Tabu	Capacity Scaling	Improvement
1	1	2.49%	1.48%	0.76%	2.48%	0.06%	-0.70%
1	5	12.31%	3.49%	2.43%	7.85%	0.29%	-2.14%
1	10	19.86%	3.55%	3.09%	12.09%	-0.14%	-3.23%
2	1	2.21%	1.31%	0.78%	1.67%	0.09%	-0.69%
2	5	9.16%	3.68%	2.64%	6.76%	0.28%	-2.36%
2	10	14.45%	4.27%	3.04%	8.99%	0.26%	-2.78%
8	1	2.96%	1.74%	1.15%	1.95%	0.33%	-0.82%
8	5	6.33%	4.14%	3.23%	6.41%	0.72%	-2.51%
8	10	8.60%	4.40%	4.11%	4.94%	0.66%	-3.45%

- LB =the optimal value or the best upper bound by CPLEX by Crainic et al.
- Gap= (UB-LB)/LB. Gaps are not real gaps.
- Nodes 10,20; Arcs 25,50,75,100,200,300; Commodities 10,25,40,50,100,200

Conclusion

- For the multi-commodity capacitated network design problem,
 - Present a strong path type formulation,
 - Propose a capacity scaling procedure combined with column and row generation techniques and a branch-and-bound method.

Conclusion

- Test the effectiveness of the capacity scaling procedure by Crainic's data.
 - For type C problem, 31 new best solutions out of 44 problems are obtained.
 - For type R problem, improvement by capacity scaling procedure is 0.69%-3.45%.